

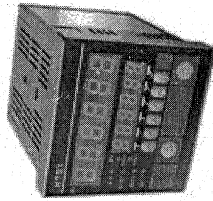
# H7JM2 Series Intelligent counterMeter operating instructions

Read carefully this instruction, if there is any question, please contact our engineer.

## Description

- Size 72\*72mm
- High-performance CPU, high-speed data processing
- Adapts to various encoders
- By changing the setting coefficient, the measurement results can be arbitrarily and more accurate
- Stable performance, strong anti-interference
- Keep data for 10 years
- Counting speed is 60K CPS

For cloth inspecting machine, rolling machine, forming machine and mechanical equipment which need measure the length of cable. It is mainly used in textile, cable, papermaking and other wire/silk strip production process automatic measuring, meter and control.



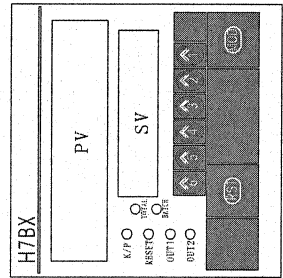
## Product Manual

### Model difference

Model	Function
H7JM2-6E2R	Power failure memory and no cumulative count Automatic reset, external terminal pulse reset Reference point calibration position Position: the decimal point Counting range: 99999-000.000-999999 Reversible E encoder 2 multiplier Reversible technology A mode

## Technical characteristics

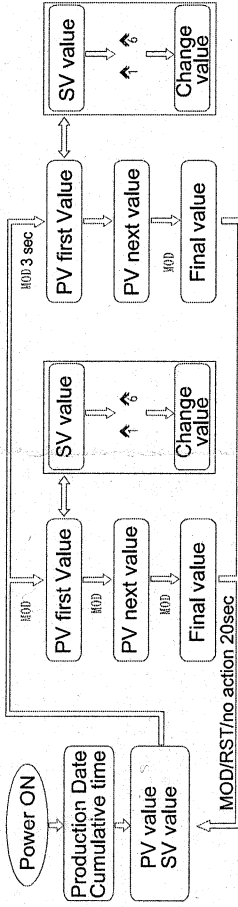
- Power supply: AC/DC 100-250V
- Auxiliary output power: DC12V, 200mA
- Input signal frequency: 0Hz-30kHz
- Input signal:  $L \leq 2V$ ;  $H \geq 30uS$  (30K CPS)
- Output response time: count arrival relay output time  $\leq 6ms$
- Corrected input response time: 0.8ms
- Dimensions: 72\*72\*85mm
- Weight: 230g
- Power consumption: less than 4W
- Capacity: AC220V 3A/DC24V 5A
- Reset pulse signal:  $L \leq 2V$ ;  $H \geq 5V$
- Input impedance: 2K
- Environment: 0-60°C; humidity  $\leq 85\%$
- Storage temperature: -20-85
- Installation method: snap-in



No	Panel	Description
1.	PV	Count value
2.	SV	Set value
3.	RESET	Reset signal input indicator
4.	K/P	Key lock indicator
5.	OUT1	Output OUT1 indicator
6.	OUT2	Output OUT2 indicator
7.	RST	Reset button
8.	MOD	Setting button
9.	↑	Set the number increase button

# H7JM2 Series Intelligent counterMeter operating instructions

## Operating Instruction



## Parameters

Short press "MOD"

Code	FUNCTION	FUNCTION
P5000	Parameter protection, this function appears when PSLE > 2 password "8327" to modify the parameters.	Relay (OUT1) action interval setting; when OUT1 is No. 1, this parameter will appear, and (OUT1) will operate within the set interval (display value is between two setting values)
d11-1	Relay (OUT1) SETTING	Relay (OUT2) action interval setting; when OUT2 is No. 1, this parameter will appear, and (OUT2) will operate within the set interval (display value is between two setting values)
d11-2	Relay (OUT1) SETTING	
Press "MOD" 3 SEC		
Code	FUNCTION	FUNCTION
P5000	Parameter protection, this function appears when PSLE > 2 password "8327" to modify the parameters.	
P-...	Pulse equivalent magnification (0.00001-99.9999); "P-..." parameter mark, can set decimal point; "P-CoEF" can set magnification value	
P-CoEF	Correction value	
5d---P		Count mode: Reversible A Mode, Encoder E mode
d11-1	Relay output mode: OUT1 No. 01-04, 11, OUT2 No 01-02, 10, 11, 12.	Memory mode: "ON" power failure memory "OFF" power failure does not remember
d11-2	Relay output delay value:	
d11-3	Setting range 0.1-9.9 sec	Set the decimal point position
LP---H	Key lock: 1: lock MOD press 3S; 2: lock RST reset; 3: lock SET press 3S; 4: lock all buttons	
PSLE-X	Password protection: PSLE-0 does not require a password; PSLE-1 only protects the second type of parameters; PSLE-2 first type and second type of parameters need to be protected	
HF--F1	Restore factory default state, password 3688	

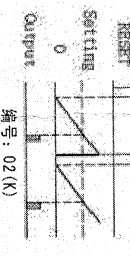
## Operating mode

Encoder E MODE	Reversible A MODE
<p>Encoder double frequency mode: Automatically determine forward rotation</p>	<p>Reversible count mode: CP1 as pulse count, CP2 as direction control pulse and automatically determine forward rotation</p>

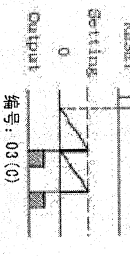
## Relay output mode description



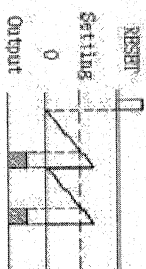
Count to "setting value", relay pull-in and keep count



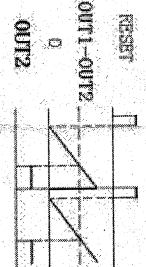
Count to "setting value", relay pull-in and delayed release then keep count. The delay time is the time set in oL-n-X



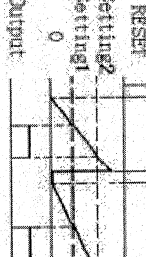
Count to "setting value", relay pull-in counter resets immediately and delayed release. The delay time is the time set in oL-n-X



Count to "setting value", relay pull-in and keep count; relay delayed release then count reset



Count to setting value (OUT1-OUT2) relay pull-in, keep count



Count between "setting 1 and setting 2", relay pull-in and keep count

### Relay Delay Time

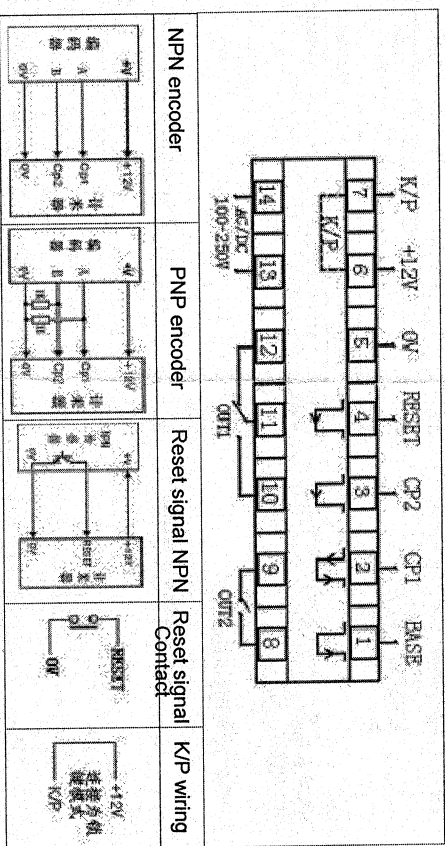
The internal scan time of the counter is 0.8ms.

Due to the mechanical delay of the relay,

So when the count reaches the set value

Need 4.5-6ms, the relay contacts can be closed

## Wiring diagrams and terminals



## Terminal description

- T13, T14 are power input terminals, and external AC/DC:100-250V power supply; (12-24VDC can be customized)
- T6 is the output power terminal, and the output is 12V/200mA for the sensor.
- T7 is the K/P button lock end, when connected to 12V, Lock button function according to lock level
- T5 is the common end, the same as the output power 0V
- T4 reset input, input signal clear
- T2, T3 are the counting input, the input signal is up and down counting
- T1 is the calibration input

## Attention

- Work environment: 0-60 Humidity 85%
- Avoid strong shocks
- Do not use in a chemical atmosphere
- Use PNP type sensor
- Try to keep the instrument away from high magnetic fields, high frequency, high pressure, etc. Input signal line: shielded line
- The output control current should not exceed the contact capacity of the relay
- Pulse equivalent (electronic gear ratio) P-CoEF=perimeter/(pulse\*2)
- Pay attention to counting speed while setting. 2000KCP is measured when the duty ratio is 1:1 and the phase difference is 90°, take into account the error, should pay attention to leaving the speed margin when setting.  
S: encoder 100ppr, shaft speed is 900 rev / min; count speed: 100 \* 900/60 (60s) = 1500 CPS
- When setting the "OUT1" relay action value, be careful about the inertia of the mechanical action. Such as: set "OUT1" action value is 200, but count to 200, controller stop, but due to inertia, it will go forward a distance to 210, inertial value is about 10. In order to eliminate inertia, we can set "OUT1" action value 200-10=190 Or set "OUT2" to use the OUT2 relay to brake before deceleration, and then slowly go to 200 and stop to ensure the accuracy.

## Application

